

$$f_y(x, y) = \frac{\partial f}{\partial y}(x, y)$$

MATH 162A Review: The Picard-Lindelöf Theorem

Facts to Know:

In differential geometry, we need to know certain quantity exists, and usually this would be equivalent to the existence to some ordinary differential equation. In differential equations, the Picard-Lindelöf theorem, also known as the Picard's existence theorem, Cauchy-Lipschitz theorem, or existence and uniqueness theorem gives a set of conditions under which an initial value problem has a unique solution.

For the equation $y' = f(x, y)$ with the initial value condition $y(t_0) = y_0$, if the function $f(x, y)$ is continuous, and the partial derivative function $f_y(x, y)$ is also continuous near the point (t_0, y_0) . Then there is an $\varepsilon > 0$, such that the solution exists on the interval $(t_0 - \varepsilon, t_0 + \varepsilon)$.

$$f(x, y) = |x| \cdot y \quad f_y(x, y) = |x|$$

$$\begin{cases} y' = f(x, y) = |x|y \\ y(t_0) = 4 \end{cases}$$



$$x' = \vec{f}(x, t).$$

$$x(t) = \begin{bmatrix} x_1(t) \\ \vdots \\ x_n(t) \end{bmatrix}$$

$\vec{f}(x, t)$ is a function $\vec{f}(x, t) = \vec{f}(x_1, \dots, x_n, t)$.

Theorem

Let $x' = \vec{f}(x, t)$, such that $x(t_0) = \vec{b} = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix}$

① $\vec{f}(x, t)$ to be continuous.

② When fixing t , $\vec{f}(x, \cdot)$ is differentiable

near $(b_1, \dots, b_n, t_0) \Rightarrow \exists \varepsilon > 0$. such that

there is a unique solution $x = x(t)$ on

$(t_0 - \varepsilon, t_0 + \varepsilon)$.

$$\left\{ \begin{array}{l} y'' = f(t, y, y') \\ y(t_0) = a \\ y'(t_0) = b \end{array} \right. \quad \left| \quad \begin{array}{l} x(t) = \begin{bmatrix} y(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix} \\ x'(t) = \begin{bmatrix} y'(t) \\ y''(t) \end{bmatrix} = \begin{bmatrix} x_2(t) \\ f(t, x_1, x_2) \end{bmatrix} \end{array} \right.$$

$$\left\{ \begin{array}{l} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}' = \begin{bmatrix} x_2 \\ f(t, x_1, x_2) \end{bmatrix} \\ \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} a \\ b \end{bmatrix} \end{array} \right.$$